ASP-based Declarative Process Mining

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- To show how Answer Set Programming can solve problems from Declarative Process Mining.
- Three problems considered: Log Generation, Conformance Checking, and Query Checking.
- Encodings share a common part.

- Intersection of Business Process Management and Data Mining.
- Getting insights into processes analyzing event logs.

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- An event consists of an activity, a timestamp and (possibly) other attributes.
- A case (or trace) is an observed sequence of events.
- An event log is a collection of cases.
- A process model is a specification of properties of cases.

- Control-flow perspective focuses on activities.
- Data-aware perspective focuses on attributes.
- Time perspective focuses on timestamps.

- Log generation [Sky+18] is the problem of generating a log compliant with a process model.
- *Conformance checking* [BMS16] is the problem of checking whether traces are compliant with a process model.
- *Query checking* [Räi+14] is the problem of finding properties of a process from the associated event log.

- Processes are set of constraints.
- Formalism used are:
 - DECLARE [APS09]
 - Linear Temporal Logic on finite traces (LTL_f) [DV13]

Template	Meaning		
Absence(a)	Activity a never happens		
Existence(a)	Activity a happens at least 1 time		
Response(a, b)	If a happens, b happens afterwards		
NotResponse(a, b)	If <i>a</i> happens, <i>b</i> doesn't happen afterwards		
RespondedExistence(a, b)	If a happens, b happens		
AlternateResponse(a, b)	If <i>a</i> happens then <i>b</i> happens without any <i>a</i> inbetween		
Precedence(a, b)	If <i>b</i> happens, then <i>a</i> happened before it		

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 \bullet Given a set ${\mathcal P}$ of propositional symbols, the syntax is defined by the following grammar:

$$\varphi ::= A \mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \mathbf{X} \varphi \mid \varphi_1 \mathbf{U} \varphi_2$$

with $A \in \mathcal{P}$.

• Common abbreviations used are:

- true, \rightarrow , \lor
- $\mathbf{F}\varphi \equiv true \mathbf{U}\varphi$
- $\mathbf{G}\varphi \equiv \neg \mathbf{F} \neg \varphi$

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$$\varphi_1 \mathbf{W} \varphi_2 \equiv \varphi_1 \mathbf{U} \varphi_2 \lor \mathbf{G} \varphi_1$$

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• Given a formula φ , a trace $\pi = \pi_1, \pi_2, \dots, \pi_{len(\pi)} \in (2^{\mathcal{P}})^+$, and a time instant *i*, with $1 \leq i \leq len(\pi)$, the semantics is defined as follows:

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$$\pi, i \models A$$
 iff $A \in \pi_i$,
• $\pi, i \models \neg \varphi$ iff $\pi, i \not\models \varphi$,
• $\pi, i \models \varphi_1 \land \varphi_2$ iff $\pi, i \models \varphi_1$ and $\pi, i \models \varphi_2$,
• $\pi, i \models \mathbf{X}\varphi$ if $i < len(\pi)$ and $\pi, i + 1 \models \varphi$,
• $\pi, i \models \varphi_1 \mathbf{U}\varphi_2$ iff $\pi, j \models \varphi_2$ for some j , with $i \le j \le len(\pi)$, and
 $\pi, k \models \varphi_1$ for all $k = i, \dots, j - 1$.

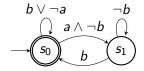
• A formula φ is true in π , and we write $\pi \models \varphi$, if $\pi, 1 \models \varphi$.

Template	LTL_f Formula
Absence(a)	$\neg Fa$
Existence(a)	Fa
Response(a, b)	${f G}(a ightarrow{f F}b)$
NotResponse(a, b)	${f G}(a ightarrow eg {f F}b)$
RespondedExistence(a, b)	${\sf F}a o {\sf F}b$
AlternateResponse(a, b)	${f G}(a o {f X}(eg a {f U} b))$
Precedence(a, b)	$\neg b \mathbf{W} a$

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- For each LTL_f formula φ there exists a NFA A_φ that accepts exactly the traces satisfying φ.
- For example to $\varphi = \mathbf{G}(a \rightarrow \mathbf{F}b)$ is associated



- An *activity* is an expression of the form $A(a_1, ..., a_{n_A})$, where A is the *activity name* and each a_i is an *attribute name*.
- An *event* is an expression of the form $e = A(v_1, ..., v_{n_A})$, where v_i is a element of the set $D_A(a_i)$ of possible values of a_i .
- A process trace is a finite sequence of events $\pi = e_1 \cdots e_n$.
- An event log is a finite set of traces.

Given a finite set of activities Act, the formulas φ of L-LTL_f over Act are inductively defined as follows:

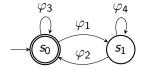
$$\varphi = true \mid A \mid a \odot a' \mid a \odot v \mid \neg \varphi \mid \varphi \land \varphi \mid \mathbf{X}\varphi \mid \varphi \mathbf{U}\varphi,$$

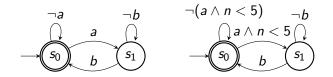
where: *a* and *a'* are attribute names from some activity in *Act*, $v \in D_A(a)$, for some $A \in Act$, \odot is an operator from $\{<, \leq, =, \geq, >\}$, and *A* is an activity name from *Act*.

- For every L-LTL_f formula φ there exists a finite-state automaton (FSA) \mathcal{A}_{φ} that accepts exactly the traces that satisfy φ (see [DV13]).
- Such automata are standard FSA with transitions labelled by event formulas (i.e. without temporal operators).

Example

The L-LTL_f formula $\varphi = \mathbf{G}(a \rightarrow \mathbf{F}b)$ can be extended as $\varphi' = \mathbf{G}((a \land n < 5) \rightarrow \mathbf{F}b)$





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- Convert specifications into automata.
- Represent automata in ASP.
- Represent traces in ASP.
- Modeling how automata read trace.
- Add generation and test rules.

ASP for DPM: data

Predicates:

- act(A): A is an activity.
- has_attr(A, N): activity A has attribute N.
- val(N, V): a possible value of attribute N is V.

Activities $a_1(int, cat)$ and $a_2()$, with $int \in \{1, ..., 10\}$ and $cat \in \{c_1, c_2, c_3\}$ becomes:

- $act(a_1)$. $has_attr(a_1, int)$. $has_attr(a_1, cat)$.
- act(a₂).
- value(int, 1..10).
- value(cat, c1). value(cat, c2). value(cat, c3).

Predicates:

- trace(A, T): activity A happens at time T.
- $has_value(N, V, T)$: attribute N has value V at time T.

Trace $a_2(), a_1(2, c_3), a_2()$ becomes:

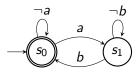
- *trace*(*a*₂, 1).
- trace(a₁, 2). has_value(int, 2, 2). has_value(cat, c₃, 2).
- *trace*(*a*₂, 3).

- *init*(*S*): *S* is the initial state.
- acc(S): S is an accepting state.
- trans(S, F, S'): there exists a transition from state S to state S' labeled with event formula F.
- holds(F, T): event formula F holds at time T.

Example

The ASP encoding of the formula $\varphi = \mathbf{G}(a \rightarrow \mathbf{F}b)$ is given by:

- *init*(*s*₀).
- $acc(s_0)$.
- $trans(s_0, 1, s_1)$.
- $holds(1, T) \leftarrow trace(a, T)$.
- $trans(s_1, 2, s_0)$.
- $holds(2, T) \leftarrow trace(b, T)$.
- $trans(s_0, 3, s_0)$.
- $holds(3, T) \leftarrow not holds(1, T), time(T).$
- $trans(s_1, 4, s_1)$.
- $holds(4, T) \leftarrow trace(A, T), A \neq b.$



For the data-aware formula $\varphi' = \mathbf{G}((a \land n < 5) \rightarrow \mathbf{F}b)$ it is sufficient to modify the rule for *holds*(1, *T*) as follows:

• $holds(1, T) \leftarrow trace(a, T), has_value(n, V, T), V < 5.$

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Predicate state models execution of automaton on trace

• state(S, T): S is current state at time T.

and updated as

- $state(S, 0) \leftarrow init(S)$.
- $state(S', T) \leftarrow state(S, T 1), trans(S, F, S'), holds(F, T).$

Problem: given an L-LTL_f formula *varphi* and trace length t, generate a trace of length t satisfying φ

Generate traces as follows

- {trace(A, T) : activity(A)} = 1 \leftarrow time(T).
- { $has_value(K, V, T)$: value(K, V)} = 1 \leftarrow $trace(A, T), has_attribute(A, K).$

Test traces as follows

• sat \leftarrow state(S, t), accepting(S).

• \leftarrow not sat.

It is given a set of traces.

- Add the trace index *i* to predicate *sat*.
- Check whether *sat*(*i*) holds.

The following predicates are introduced

- var(V): V is a variable.
- assgnmt(V, A): activity A is assigned to variable V.

The body of the rule for *holds* is modified by replacing trace(act, T) with trace(A, T), assgnmt(v, A), with v being the variable in place of activity act.

Then for generating

• {assgnmt(V, A) : activity(A)} = 1 $\leftarrow var(V)$.

and for testing we check that the formula is satisfied by the trace.

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Consider formula $\varphi = \mathbf{G}((?A \land number < 5) \rightarrow \mathbf{F}b).$

Rule for holds(1, T) is:

 $holds(1, T) \leftarrow trace(A, T), assgnmt(varA, A), has_value(n, V, T), V < 5.$

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Experiments: Log Generation

# constr. \rightarrow	3	5	7	10	
Trace len \downarrow					
10	35975	35786	36464	37688	
15	50649	51534	54402	54749	
20	69608	70342	73122	73222	
25	85127	85598	87065	89210	
30	101518	101882	106062	107520	
10	595	614	622	654	
15	876	894	904	956	
20	1132	1155	1178	1250	
25	1364	1413	1444	1543	
30	1642	1701	1746	1874	

Table: Time (in ms) for generating a log of 10000. Above: Results obtained with MP-Declare Log Generator, a state-of-the-art tool. Below: our results.

$Tool \to$	ASP	Declare Analyzer
Trace Len \downarrow		
10	665	598
15	1100	805
20	1456	1092
25	2071	1273
30	2407	1337

Table

Time (in ms) for checking a log of 1000 traces against a model of 10 constraints.

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Constraints \rightarrow	Existence	Responded	Response	Chain	Absence	Not Resp.	Not Resp.	Not Chain
Trace len ↓	1	Existence		Response		Existence		Response
10	521	736	534	503	566	783	602	385
15	704	1113	801	788	784	1180	879	606
20	1321	1675	1143	1128	1373	1821	1304	865
25	1397	3218	1528	1561	1562	2823	1807	1104
30	1674	2878	1824	1906	1905	2784	2028	1301

Table: Time (in ms) for checking different DECLARE constraints (with both activation and target activity, if any, unknown) against a log of 1000 traces

Our approach

- outperforms the SoA tool MP-Declare Log Generator [Sky+18]
- shows results comparable wrt SoA tool Declare Analyzer [BMS16]
- show the feasibility of data-aware Query checking

Note

- more general specifications.
- code not optimized.

Provided

- ASP encoding of data-aware Log Generation, Conformance Checking, and Query Checking
- Performance evaluation wrt state-of-the-art

Future work

- add time-perspective (i.e. timestamp)
- correlation condition

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